

University of Technology- Computer Science

Material: Microprocessors

Stage: Second Class Year: 2024-2025 Semester :2nd course Assist lecturer Mohammed Thamer

Lect1 & 2: Load & Move Instructions with Practical Examples

1. Introduction to Load & Move Instructions

The **MOV** instruction is the primary instruction used for data transfer in **8086**. It moves data between registers, memory, or I/O ports without altering the value.

MOV Instruction Format:

MOV destination, source

- Transfers source operand to destination operand.
- Does not modify any flag registers.

Rules for MOV Instruction:

- Both operands cannot be memory locations.
- **Operands must be of the same size** (8-bit or 16-bit).
- Immediate values cannot be moved directly to segment registers (e.g., MOV DS, 1234H is invalid).

2. Register Addressing and Examples

Example 1: Moving Data Between Registers

MOV AX, BX ; Copy the value from BX to AX MOV CL, DL ; Copy the value from DL to CL MOV DX, 1234H ; Load immediate value into DX

Example 2: Moving Data from Memory to Register

MOV AX, [2000H] ; Move data from memory location 2000H to AX MOV [3000H], BX ; Store BX value into memory location 3000H

Example 3: Moving Immediate Value to Register

MOV CX, 0F5H ; Load CX with immediate value F5H MOV AX, 45H ; Load AX with immediate value 45H

4. Direct vs Indirect Addressing

• Direct Addressing: Uses a specific memory address in the instruction.

• Indirect Addressing: Uses a register to hold the address pointing to memory.

Example 4: Direct Addressing

MOV AL, [5000H] ;Load value from memory address 5000H into AL

Example 5: Indirect Addressing

MOV SI, 5000H ; Load address into SI MOV AL, [SI] ; Load value from memory location pointed by SI

5. Extended Examples and Practical Applications

Example 6: Copying Data Between Registers

MOV AX, 1234H MOV BX, AX ; Copy AX to BX

Example 7: Using Immediate Value for Data Transfer

MOV DX, 0A1H ; Load DX with immediate value MOV CX, 0B2H ; Load CX with immediate value

Example 8: Moving Data Between Memory Locations Using Indirect Addressing

MOV SI, 2000H MOV DI, 3000H MOV AX, [SI] ; Load value from memory location 2000H MOV [DI], AX ; Store the loaded value at memory location 3000H

6. Exercises and Solutions

Question 1: Moving Data Between Registers

Q: Write a program to move data from AX to BX and from CX to DX.

Solution:

MOV BX, AX ; Move data from AX to BX MOV DX, CX ; Move data from CX to DX

Question 2: Using Immediate Values

Q: Load 0A1H into DX and 0B2H into CX.

Solution:

MOV DX, 0A1H ; Load DX with immediate value MOV CX, 0B2H ; Load CX with immediate value

Question 3: Direct vs Indirect Addressing

Q: Move the value stored at memory address **5000H** into **AL** using **direct addressing**, and then use **indirect addressing** to load the same value.

Solution:

MOV	AL,	[5000H]	;	Direct addressing	
MOV	SI,	5000н	;	Load address into Si	Γ
MOV	AL,	[SI]	;	Indirect addressing	

Question 4: Moving Data Between Memory Locations

Q: Write a program to copy a block of data from one memory location to another.

Solution:

MOV SI, 2000H	; Source memory location
MOV DI, 3000H	; Destination memory location
MOV AX, [SI]	; Load data from source
MOV [DI], AX	; Store data at destination

Lect3: Arithmetic Instructions (ADD, SUB, MUL, DIV)

1. Introduction to Arithmetic Instructions

Arithmetic instructions allow the processor to perform addition, subtraction, multiplication, and division.

Instruction			Description
ADD	dest,	src	Adds src to dest, result stored in dest.
SUB	dest,	src	Subtracts src from dest, result stored in dest.
MUL	src		Multiplies AX by src (for 16-bit), or AL by src (for 8-bit).
IMUI	_ src		Signed multiplication.

Common Arithmetic Instructions:

DIV src	Unsigned division. Quotient in AX, remainder in DX (for 16-bit).
IDIV src	Signed division.

2. Arithmetic Operations and Examples

Example 1: Addition of Two Registers

MOV AX, 05H ; Load AX with 5 MOV BX, 03H ; Load BX with 3 ADD AX, BX ; AX = AX + BX (AX = 5 + 3 = 8)

Example 2: Subtraction of Two Registers

MOV	AX,	09н	;	Load	AX	with	9						
MOV	BX,	04H	;	Load	вх	with	4						
SUB	AX,	BX	;	AX =	AX	- BX	(AX	=	9	-	4	=	5)

Example 3: Multiplication of Two Numbers

MOV	AL,	04H	;	Load	AL	with	4						
MOV	BL,	02H	;	Load	\mathtt{BL}	with	2						
MUL	BL		;	AL =	AL	* BL	(AL	=	4	*	2	=	8)

Example 4: Division of Two Numbers

MOV AX, 10H ; Load AX with 16 MOV BL, 04H ; Load BL with 4 DIV BL ; AX = AX / BL (Quotient in AL, Remainder in AH)

4. Exercises and Solutions

Question 1: Perform Addition of Immediate Values

Q: Write a program to add **0AH** and **05H** and store the result in AX.

Solution:

MOV AX, 0AH ; Load AX with A (10 in decimal) ADD AX, 05H ; AX = AX + 5

Question 2: Subtraction Using Registers

Q: Subtract 07H from 15H and store the result in BX.

Solution:

MOV BX, 15H ; Load BX with 15 SUB BX, 07H ; BX = BX - 7

Question 3: Multiply Two Numbers Using MUL

Q: Multiply 03H and 05H, store the result in AX.

Solution:

MOV	AL,	03н	;	Load	AL	with	3
MOV	BL,	05н	;	Load	\mathtt{BL}	with	5
MUL	BL		;	AL =	AL	* BL	

Question 4: Division of Numbers

Q: Divide 20H by 04H, store the quotient in AL and remainder in AH.

Solution:

MOV	AX,	20н	;	Load AX with 32 (decimal)
MOV	BL,	04H	;	Load BL with 4
DIV	BL		;	Quotient in AL, Remainder in AB

Lect4: Examples of Arithmetic Instructions & Jump Operations

1. Introduction to Jump Instructions

Jump instructions allow control flow changes in assembly programming. These instructions alter the execution sequence based on specific conditions.

Types of Jump Instructions:

Instruction	Description
JMP label	Unconditional jump to a specified label.
JZ label	Jump if the Zero flag (ZF) is set.
JNZ label	Jump if the Zero flag (ZF) is not set.
JE label	Jump if Equal (same as JZ).
JNE label	Jump if Not Equal (same as JNZ).
JL label	Jump if Less (signed comparison).
JG label	Jump if Greater (signed comparison).

2. Arithmetic Operations and Jumps with Examples

Example 1: Addition and Conditional Jump

MOV	AX,	5	;	Load AX with 5
MOV	BX,	3	;	Load BX with 3
ADD	AX,	BX	;	AX = AX + BX
CMP	AX,	10	;	Compare AX with 10
JNZ	NOT	EQUAL	;	Jump if AX is not equal to 10

Example 2: Subtraction and Jump if Zero

MOV AX, 10	;	Load	AX	with	10			
MOV BX, 10	;	Load	BX	with	10			
SUB AX, BX	;	AX =	AX	- BX	(AX	= 10	-10 =	0)
JZ EQUAL	;	Jump	to	EQUAI	L if	AX is	s zero	

Example 3: Looping Using Jumps

```
MOV CX, 5 ; Counter
LOOP_START:
DEC CX ; Decrease CX by 1
JNZ LOOP_START ; Repeat loop if CX is not zero
```

3. Exercises and Solutions

Question 1: Compare Two Numbers and Jump

Q: Write a program to compare two values and jump to a label if they are equal.

Solution:

MOV AX, 10	;	Load AX with 10
MOV BX, 10	;	Load BX with 10
CMP AX, BX	;	Compare AX with BX
JE EQUAL	;	Jump if AX == BX

Question 2: Loop Execution Until Zero

Q: Write a program to decrement a counter and loop until it reaches zero.

Solution:

MOV CX, 5 ; Initialize loop counter

LOOP_LABEL: DEC CX ; Decrement CX JNZ LOOP_LABEL ; Repeat if CX is not zero

Question 3: Conditional Jump Based on Addition Result

Q: Add 05H and 07H and jump if the result is greater than 0AH.

Solution:

MOV AL, 05H ADD AL, 07H CMP AL, 0AH JG GREATER

Lect5: Logical Instructions, Shift & Rotate Operations

1. Logical Instructions Overview

Logical operations allow manipulation of individual bits within a byte or word.

Instruction	Description
AND dest, src	Performs bitwise AND between dest and src.
OR dest, src	Performs bitwise OR between dest and src.
XOR dest, src	Performs bitwise XOR (exclusive OR) between dest and src.
NOT dest	Inverts all bits in dest.
SHL dest, n	Shifts bits of dest left by n places.
SHR dest, n	Shifts bits of dest right by n places.
ROL dest, n	Rotates bits of dest left by n places.
ROR dest, n	Rotates bits of dest right by n places.

Common Logical Instructions:

3. Logical Operations and Examples

Example 1: Bitwise AND Operation

MOV AL, OFOH ; Load AL with 11110000B AND AL, OF5H ; AL = AL AND 11110101B **Example 2: Bitwise OR Operation**

MOV AL, 0A0H ; Load AL with 10100000B OR AL, 05H ; AL = AL OR 00000101B

Example 3: Logical Shift Left

MOV AL, 05H ; Load AL with 00000101B SHL AL, 1 ; AL = AL shifted left by 1 (00001010B)

Lect6: Examples of Logical Instructions

1. Practical Applications and Examples

Example 4: Bitwise XOR Operation

MOV AL, OFFH ; Load AL with 1111111B XOR AL, OFOH ; AL = AL XOR 1110000B

Example 5: Logical NOT Operation

MOV AL, 0F0H ; Load AL with 11110000B NOT AL ; AL = NOT AL (00001111B)

Example 6: Rotate Left Operation

MOV AL, 85H ; Load AL with 10000101B ROL AL, 1 ; Rotate left by 1 (00001011B)

2. Exercises and Solutions

Question 1: Bitwise AND Operation

Q: Perform a bitwise AND operation between OAAH and OFOH.

Solution:

MOV AL, OAAH ; Load AL with 10101010B AND AL, OFOH ; AL = AL AND 11110000B

Question 2: Shift Left Operation

Q: Shift the value 3CH left by 2 bits and store the result in AL.

Solution:

MOV AL, 3CH ; Load AL with 00111100B SHL AL, 2 ; Shift AL left by 2 (11110000B)

Question 3: Rotate Right Operation

Q: Rotate the value OC3H right by 1 bit.

Solution:

MOV AL, 0C3H ; Load AL with 11000011B ROR AL, 1 ; Rotate right by 1 (01100001B)

Lect7: The Addressing Mode in 8-bit Register

1. Addressing Modes Overview

Addressing modes determine how an instruction accesses operands in memory or registers.

Types of Addressing Modes in 8-bit Registers:

Addressing Mode Description		
Immediate	Operand is specified directly in the instruction.	
Register	Operand is in a register.	
Direct	Address of the operand is specified in the instruction.	
Indirect	Register holds the address of the operand.	
Indexed	Uses an index register (SI or DI) to determine the operand's address.	

2. Addressing Mode Examples

Example 1: Immediate Addressing Mode

MOV AL, 0AH ; Load AL with immediate value 0AH

Example 2: Register Addressing Mode

MOV BL, AL ; Copy the value from AL to BL

Example 3: Direct Addressing Mode

MOV AL, [2000H] ; Load AL from memory location 2000H

Example 4: Indirect Addressing Mode

MOV SI, 3000H ; Load address 3000H into SI MOV AL, [SI] ; Load AL with value from memory location 3000H

Example 5: Indexed Addressing Mode

MOV SI, 2000H ; Base address MOV AL, [SI+5] ; Load AL with value at address 2005H

4. Exercises and Solutions

Question 1: Immediate and Register Addressing

Q: Load 05H into AL and copy it to BL.

Solution:

MOV AL, 05H ; Load AL with 05H MOV BL, AL ; Copy AL to BL

Question 2: Direct Addressing Mode

Q: Store the value 0AH at memory address 3000H.

Solution:

MOV AL, OAH MOV [3000H], AL ; Store AL value at memory 3000H

Question 3: Indirect Addressing Mode

Q: Load the value from memory location **4000H** into AL using SI.

Solution:

MOV SI, 4000H MOV AL, [SI]

Lect8: Examples of Direct and Immediate Register Addressing

1. Addressing Mode Examples

Example 1: Immediate Addressing Mode

MOV AL, 0AH ; Load AL with immediate value 0AH MOV BX, 1234H ; Load BX with immediate value 1234H

Example 2: Direct Addressing Mode

MOV AL, [2000H] ; Load AL from memory location 2000H MOV [3000H], AL ; Store AL value at memory location 3000H

Example 3: Register Addressing Mode

MOV DL, AL ; Copy AL to DL MOV CX, DX ; Copy DX to CX

2. Exercises and Solutions

Question 1: Direct and Immediate Addressing

Q: Load 0FH into AL and store it in memory location 4000H.

Solution:

MOV AL, OFH ; Load AL with immediate value MOV [4000H], AL ; Store AL value at memory 4000H

Question 2: Register to Register Transfer

Q: Move the value in **AX** to **BX**, then move it to **DX**.

Solution:

MOV BX, AX ; Copy AX to BX MOV DX, BX ; Copy BX to DX

Question 3: Memory to Register Transfer

Q: Load a value from memory 5000H into AL, then move it to CL.

Solution:

MOV AL, [5000H] ; Load value from memory 5000H into AL MOV CL, AL ; Move AL value to CL

Lect9: The Addressing Mode in 16-bit Register

1. Addressing Modes Overview

Addressing modes determine how an instruction accesses operands in memory or registers.

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Addressing Mode	Description
Immediate	Operand is specified directly in the instruction.
Register	Operand is in a register.
Direct	Address of the operand is specified in the instruction.
Indirect	Register holds the address of the operand.
Base	Uses a base register (BX or BP) to access memory.
Index	Uses an index register (SI or DI) to determine the operand's address.
Base-Index	Combines base and index registers for memory addressing.

2. Addressing Mode Examples

Example 1: Immediate Addressing Mode

MOV AX, 1234H ; Load AX with immediate value 1234H

Example 2: Register Addressing Mode

MOV DX, AX ; Copy AX to DX

Example 3: Direct Addressing Mode

MOV AX, [2000H] ; Load AX from memory location 2000H

Example 4: Indirect Addressing Mode

MOV BX, 3000H ; Load address 3000H into BX MOV AX, [BX] ; Load AX with value from memory location 3000H

Example 5: Base-Index Addressing Mode

MOV BX, 2000H ; Base address MOV SI, 10H ; Offset MOV AX, [BX+SI] ; Load AX with value at address (2000H + 10H)

3. Exercises and Solutions

Question 1: Immediate and Register Addressing

Q: Load 1234H into AX and move it to BX.

Solution:

MOV AX, 1234H ; Load AX with immediate value MOV BX, AX ; Copy AX to BX

Question 2: Direct Addressing Mode

Q: Load a value from memory **4000H** into AX.

Solution:

MOV AX, [4000H] ; Load AX from memory 4000H

Question 3: Base-Index Addressing Mode

Q: Load a value from [3000H + SI] into AX, where SI = 10H.

Solution:

MOV BX, 3000H MOV SI, 10H MOV AX, [BX+SI]

Lect10: Examples of Direct, Indirect, Base, Index, and Base-Index Register Addressing

1. Addressing Modes in Practice

Addressing Mode	Description	
Direct	Operand is stored at a specific memory address.	
Indirect	Operand is stored at a memory address pointed to by a register.	
Base	Uses a base register (BX, BP) for memory access.	
Index	Uses an index register (SI, DI) for offset memory access.	
Base-Index	Combines base and index registers for complex memory access.	

2. Addressing Mode Examples

Example 1: Direct Addressing Mode

MOV AX, [2000H] ; Load AX from memory location 2000H

Example 2: Indirect Addressing Mode

MOV BX, 3000H ; Load address 3000H into BX MOV AX, [BX] ; Load AX with value from memory location 3000H

Example 3: Base-Index Addressing Mode

```
MOV BX, 2000H ; Base address
MOV SI, 10H ; Offset
MOV AX, [BX+SI] ; Load AX with value at address (2000H + 10H)
```

3. Exercises and Solutions

Question 1: Direct Addressing Mode

Q: Load a value from memory **5000H** into AX.

Solution:

MOV AX, [5000H] ; Load AX from memory 5000H

Question 2: Base-Index Addressing Mode

Q: Load a value from [3000H + SI] into AX, where SI = 10H.

Solution:

MOV BX, 3000H MOV SI, 10H MOV AX, [BX+SI]

Lect11: The Addressing Mode in 32-bit Register

1. Addressing Modes in 32-bit Registers

32-bit addressing modes in the **8086 microprocessor** provide more flexibility and allow efficient memory access. The common addressing modes are:

Addressing Mode	Description

Direct Addressing	The operand is stored at a specific memory address mentioned in the
	instruction.
Register Addressing The operand is stored in a 32-bit register.	
Indirect Addressing	A register contains the memory address of the operand.
Base Addressing	A base register (EBX, EBP) holds the base memory address.
Index Addressing	An index register (ESI, EDI) is used for offset memory access.
Base-Index	Combines a base register and an index register for complex memory
Addressing	operations.

2. Addressing Mode Examples in 32-bit Registers

Example 1: Direct Addressing Mode

MOV EAX, [2000H] ; Load EAX from memory location 2000H

Example 2: Register Addressing Mode

MOV ECX, EAX ; Copy value from EAX to ECX

Example 3: Indirect Addressing Mode

MOV EBX, 3000H ; Load address 3000H into EBX MOV EAX, [EBX] ; Load EAX with value from memory location 3000H

Example 4: Base Addressing Mode

MOV EBP, 4000H ; Load base address into EBP MOV EAX, [EBP] ; Load EAX with value from base address

Example 5: Base-Index Addressing Mode

```
MOV EBX, 5000H ; Load base address into EBX
MOV ESI, 20H ; Load offset into ESI
MOV EAX, [EBX+ESI] ; Load value at address (5000H + 20H) into
EAX
```

Lect12: Examples of Direct, Indirect, Base, Index, and Base-Index Register Addressing in 32-bit Registers

1. Addressing Modes in Practice (32-bit Registers)

Addressing Mode	Description
Direct	Operand is stored at a specific memory address.
Indirect	Operand is stored at a memory address pointed to by a register.
Base	Uses a base register (EBX, EBP) for memory access.
Index	Uses an index register (ESI, EDI) for offset memory access.
Base-Index	Combines base and index registers for complex memory access.

2. Additional Addressing Mode Examples in 32-bit Registers

Example 6: Indexed Addressing Mode

```
MOV EDI, 6000H ; Load base address into EDI
MOV EAX, [EDI+10H] ; Load value at address (6000H + 10H) into
EAX
```

Example 7: Complex Base-Index Addressing Mode

MOV EBX, 7000H ; Load base address into EBX MOV ESI, 30H ; Load offset into ESI MOV EAX, [EBX+ESI] ; Load value at address (7000H + 30H) into EAX

3. Exercises and Solutions

Question 1: Using Indirect Addressing

Q: Load a value from memory location **8000H** into EAX using indirect addressing.

Solution:

MOV EBX, 8000H ; Load memory address into EBX MOV EAX, [EBX] ; Load value from memory into EAX

Question 2: Using Base-Index Addressing

Q: Load a value from [9000H + SI] into EAX, where SI = 50H.

Solution:

```
MOV EBX, 9000H ; Load base address into EBX
MOV ESI, 50H ; Load index offset into ESI
MOV EAX, [EBX+ESI] ; Load value at address (9000H + 50H) into
EAX
```

Lect13: Bit Scan and Bit Test Register

1. Bit Scan and Bit Test Instructions

Bit Scan Instructions:

Instruction			Description
BSF	dest,	src	Finds the first set bit (1) in src and stores the position in dest.
BSR	dest,	src	Finds the last set bit (1) in src and stores the position in dest.

Bit Test Instructions:

Instruction	Description
BT src, bit	Tests a specific bit in src and sets Carry Flag (CF) if it is 1.
BTC src, bit	Tests and complements (toggles) a specific bit in src.
BTR src, bit	Tests and resets (clears) a specific bit in src.
BTS src, bit	Tests and sets (turns on) a specific bit in src.

2. Bit Scan and Bit Test Examples

Example 1: Using BSF to Find First Set Bit

MOV EAX, 0B8H ; Binary: 10111000B BSF ECX, EAX ; ECX = Position of first set bit (3)

Example 2: Using BT to Test a Bit

MOV AX, 5	;	Binary: 00000101B
BT AX, 2	;	Test bit 2 (CF = 1 since bit 2 is set)

Example 3: Using BTS to Set a Bit

MOV BX, 0H ; BX = 0000000B BTS BX, 4 ; Set bit 4 (BX = 00010000B)

Example 4: Using BTR to Clear a Bit

MOV DX, 0FH ; DX = 00001111B BTR DX, 3 ; Clear bit 3 (DX = 00000111B)

Lect14: Examples of Bit Scan and Bit Test Instructions

1. Advanced Examples and Practical Applications

Example 5: Using BSR to Find the Highest Set Bit

MOV EAX, 0F0H ; Binary: 11110000B BSR ECX, EAX ; ECX = Position of highest set bit (7)

Example 6: Toggling a Bit with BTC

MOV	AX,	4	;	AX = 00000100B
BTC	AX,	2	;	Toggle bit 2 (AX = $0000000B$)
BTC	AX,	2	;	Toggle bit 2 again $(AX = 00000100B)$

Example 7: Using Bit Test for Conditional Execution

MOV CX, 2	;	CX =	0000001	L0B	
BT CX, 1	;	Test	bit 1		
JC BIT_IS	SET ;	Jump	if bit	is	set

Example 8: Clearing a Bit with BTR and Checking Flag

MOV DX, 3 ; DX = 00000011B
BTR DX, 0 ; Clear bit 0 (DX = 00000010B)
JNC BIT CLEARED ; Jump if bit was already clear

2. Exercises and Solutions

Question 1: Using BSF to Find First Set Bit

Q: Given AX = 01011000B, find the position of the first set bit.

Solution:

MOV AX, 58H ; Binary: 01011000B BSF BX, AX ; BX = Position of first set bit (3)

Question 2: Toggling a Bit

Q: Toggle bit 5 of register CX using BTC.

Solution:

MOV CX, 20H ; Binary: 00100000B BTC CX, 5 ; Toggle bit 5 (CX = 0000000B)

Question 3: Testing and Setting a Bit

Q: Test bit 7 of DX, and if it is 0, set it using BTS.

Solution:

MOV DX, 10H ; Binary: 00010000B
BT DX, 7 ; Test bit 7
JNC SET_BIT ; Jump if bit is clear
BTS DX, 7 ; Set bit 7 (DX = 10010000B)

Lect15: General Examples

1. Comprehensive Assembly Programming Examples

Example 1: Arithmetic and Logical Operations Combined

MOV	AX,	5	;	Load AX with 5
ADD	AX,	3	;	AX = AX + 3 ($AX = 8$)
AND	AX,	OFH	;	Apply bitmask (AX = 8 AND 15 = 8)

Example 2: Looping with Conditional Execution

MOV CX, 5	;	Set loop counter
LOOP_START:		
DEC CX	;	Decrease counter
JNZ LOOP_START	;	Repeat if CX is not zero

Example 3: String Manipulation (Copying Data)

MOV	SI, 1000H	;	Source address
MOV	DI, 2000H	;	Destination address
MOV	CX, 10	;	Number of bytes to copy
REP	MOVSB	;	Repeat move operation for CX times

Example 4: Stack Operations and Subroutines

```
CALL SUB_ROUTINE ; Call a subroutine
...
SUB_ROUTINE:
PUSH AX ; Save AX on stack
MOV AX, 10H ; Modify AX
POP AX ; Restore AX
RET ; Return to main program
```

Example 5: Interrupts and I/O Operations

MOV AH, 09H ; DOS interrupt for printing string MOV DX, OFFSET MESSAGE INT 21H ; Call DOS interrupt ... MESSAGE DB 'Hello, World!\$', 0

2. Exercises and Solutions

Question 1: Combining Arithmetic and Logical Operations

Q: Write an assembly program that adds **07H** and **09H**, then applies a bitmask OFH to the result.

Solution:

MOV	AL,	07H	;	Load AL with	07н			
ADD	AL,	09н	;	AL = AL + 09H	(AL =	10H)		
AND	AL,	OFH	;	Apply bitmask	(AL =	10H AND	0FH =	0H)

Question 2: Implementing a Counter Using Loops

Q: Create an assembly program that decrements CX from 5 to 0 using a loop.

Solution:

MOV CX, 5	;	Set loop counter
LOOP_LABEL:		
DEC CX	;	Decrease CX by 1
JNZ LOOP_LABEL	;	Repeat if CX is not zero

Question 3: Using Stack Operations in Subroutines

Q: Implement a subroutine that saves **AX** and modifies it, then restores the original value.

Solution:

CALL MY_SUB	;	Call the subroutine
• • •		
MY_SUB:		
PUSH AX	;	Save AX on stack
MOV AX, 20H	;	Modify AX
POP AX	;	Restore original AX

RET

Question 4: Printing a String Using an Interrupt

Q: Write a program that prints HELLO using an interrupt.

Solution:

MOV AH, 09H ; DOS interrupt for printing string MOV DX, OFFSET HELLO_MSG INT 21H ; Call DOS interrupt ... HELLO_MSG DB 'HELLO\$', 0